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BSc, MSci and MSc EXAMINATIONS (MATHEMATICS)
May - June 2023

## MATH60022/70022 Finite Elements: Numerical Analysis and Implementation

The following information must be completed:
Is the paper suitable for resitting students from previous years:
Yes for all 3rd year students
Yes for 4th year/MSc students who took the course in 2021-2022 and 2020-2021
No for 4th year/Msc students from previous years (different topic for mastery question)
Category A marks: available for basic, routine material (excluding any mastery question) ( 40 percent $=32 / 80$ for 4 questions):
1(a) 8 marks; 2(a) 8 marks; 1(a) 3 marks; 4(a) 10 marks
Category B marks: Further 25 percent of marks (20/80 for 4 questions) for demonstration of a sound knowledge of a good part of the material and the solution of straightforward problems and examples with reasonable accuracy (excluding mastery question): 1(b) 5 marks; 2(b) 5 marks; 3(b) 5 marks; 4(b) 6 marks

Category C marks: the next 15 percent of the marks ( $=12 / 80$ for 4 questions) for parts of questions at the high 2:1 or 1st class level (excluding mastery question):
1(c) 3 marks; 2(c) 3 marks; 3(c) 3 marks; 4(c) 4 marks
Category D marks: Most challenging 20 percent (16/80 marks for 4 questions) of the paper (excluding mastery question):
1(d) 4 marks; 2(d) 4 marks; 3(d) 4 marks
Signatures are required for the final version:

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## TEMPORARY FRONT PAGE

BSc, MSc and MSci EXAMINATIONS (MATHEMATICS)

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\text { May - June } 2023
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This paper is also taken for the relevant examination for the Associateship of the Royal College of Science.

Finite Elements: Numerical Analysis and Implementation

Date: ??
Time: ??
Time Allowed: 2 Hours for MATH60022 paper; 2.5 Hours for MATH70022 papers
This paper has 4 Questions (MATH96 version); 5 Questions (MATH97 versions).
Statistical tables will not be provided.

- Credit will be given for all questions attempted.
- Each question carries equal weight.

1. (a) Let $(K, P, \mathcal{N})$ be a finite element.
(i) Provide a definition of the nodal variables $\mathcal{N}$.
(ii) What does it mean for $\mathcal{N}$ to determine $\mathcal{P}$ ?
(b) Let $(K, P, \mathcal{N})$ be defined by:

* $K$ is a triangle with vertices $z_{1}, z_{2}$ and $z_{3}$.
* $P$ is $P_{1}+\stackrel{\circ}{P}_{3}$, where $P_{1}$ are the linear polynomials, and $\stackrel{\circ}{P}_{3}$ is the subspace of the cubic polynomials $P_{3}$ that vanish on the boundary of $K$,
* $\mathcal{N}=\left(N_{1}, N_{2}, N_{3}, N_{4}\right)$, where $N_{i}[u]=u\left(z_{i}\right), i=1,2,3$, and $N_{4}[u]=u\left(z^{*}\right)$, where $z^{*}=z_{1}+\left(z_{2}-z_{1}\right) / 3+\left(z_{3}-z_{1}\right) / 3$.
(i) Let $u \in P$. Show that $u$ is linear when restricted to each of the edges of $K$. (1 mark)
(ii) Show that $\mathcal{N}$ determines $P$.
(c) Find the nodal basis function $\phi_{4}$.
(d) Let $u$ solve $-\nabla^{2} u=f$ in the unit square $\Omega$ with boundary conditions $u=0$ on all sides of the square.
Let $V$ be the finite element space constructed on a triangulation $\mathcal{T}$ of the unit square, using the finite element considered in Part (b).
Let $u_{h} \in \stackrel{\circ}{V}$ solve the finite element variational problem,

$$
\begin{equation*}
\int_{\Omega} \nabla u_{h} \cdot \nabla v \mathrm{~d} x=\int_{\Omega} f v \mathrm{~d} x, \quad \forall v \in \stackrel{\circ}{V} \tag{1}
\end{equation*}
$$

where $\stackrel{\circ}{V}$ is the subspace of $V$ containing functions that vanish on the boundary $\partial \Omega$ of $\Omega$. Let $b \in V$ be a function that vanishes everywhere except for one triangle $K$ in $\mathcal{T}$. Further, let $b=\phi_{4}$ in $K$.
(i) Show that

$$
\begin{equation*}
\int_{K} \nabla\left(u-u_{h}\right) \cdot \nabla b \mathrm{~d} x=0 . \tag{2}
\end{equation*}
$$

(ii) Hence, show that

$$
\int_{K} u-u_{h} \mathrm{~d} x=\int_{\partial K}\left(u-u_{h}\right) \gamma(x) \mathrm{d} S
$$

where $\partial K$ is the boundary of $K$ and $\gamma(x)$ is a known function supported on $\partial K$. Give the definition of $\gamma(x)$.
2. (a) Consider a finite element $(K, P, \mathcal{N})$, with nodal basis $\left\{\phi_{i}\right\}_{i=1}^{n}$.
(i) Provide a definition of local interpolation operator $I_{K}$.
(ii) Show that

$$
\begin{equation*}
N_{i}\left[I_{K}(v)\right]=N_{i}[v], \quad i=1, \ldots, n . \tag{2marks}
\end{equation*}
$$

(iii) Show that $I_{K}$ is the identity when restricted to $P$.
(b) For a nodal variable $N \in P^{\prime}$, we define the norm $\|N\|_{C^{l}(K)^{\prime}}$ by

$$
\begin{equation*}
\|N\|_{C^{l}(K)^{\prime}}=\sup _{0<\|u\|_{C^{l}(K)}} \frac{|N[u]|}{\|u\|_{C^{l}(K)}^{l}}, \tag{5}
\end{equation*}
$$

where

$$
\begin{equation*}
\|u\|_{C^{l}(K)}=\sup _{x \in K, r=0, \ldots, l}\left|D_{r} u(x)\right| \tag{6}
\end{equation*}
$$

and $D_{r}$ is the $r$ th derivative. Show that

$$
\begin{equation*}
\left\|I_{K}(u)\right\|_{H^{k}(K)} \leq C_{1}\|u\|_{C^{l}(K)} \tag{7}
\end{equation*}
$$

where

$$
\begin{equation*}
C_{1}=\sum_{i=1}^{n}\left\|\phi_{i}\right\|_{H^{k}\left(K_{1}\right)}\left\|N_{i}\right\|_{C^{l}(K)^{\prime}} \tag{8}
\end{equation*}
$$

(c) You may assume the Sobolev inequality for continuous functions $u \in C^{l}(K)$. This states that there exists a constant $0<C_{2} \leq \infty$, depending only on the shape and size of $K$, such that

$$
\begin{equation*}
\|u\|_{C^{l}(K)} \leq C_{2}\|u\|_{H^{k}(K)}, \tag{9}
\end{equation*}
$$

provided that $k>d / 2+l$, where $d$ is the dimension of $K$.
Show that there exists $0<C_{3} \leq \infty$, such that

$$
\begin{equation*}
\left\|I_{K}(u)\right\|_{H^{k}(K)} \leq C_{3}\|u\|_{H^{k}(K)} \tag{10}
\end{equation*}
$$

stating any assumptions that you make about $k, l$, and $d$.
(d) For each finite element below, consider $u \in H^{2}(K)$, and give all the values of $k$ for which $\left\|I_{K}(u)\right\|_{H^{k}(K)}$ is finite, justifying your answer.
(i) The degree $m$ Lagrange elements on the interval $[0,1]$.
(ii) The degree $m$ Lagrange elements on a triangle.
(iii) The degree $m$ Lagrange elements on a tetrahedron.
(iv) The cubic Hermite elements (nodal variables are point evaluations on vertices plus cell centre, and derivative evaluations on vertices) on a triangle.
3. (a) Let $(K, P, \mathcal{N})$ be a finite element.
(i) Provide a definition of a local geometric decomposition for $(K, P, \mathcal{N})$.
(ii) What does it mean for a local geometric decomposition to be $C^{0}$ ?
(b) Let $(K, P, \mathcal{N})$ be a finite element with a $C^{0}$ local geometric decomposition. Let $\mathcal{T}$ be a triangulation, and let $V$ be a finite element space constructed on $\mathcal{T}$ using $(K, P, \mathcal{N})$ and the local geometric decomposition. Show that $V$ is a $C^{0}$ finite element space.


Figure 1: Diagram for parts 3(c-d)
(c) The diagram in Figure 1 shows a mesh which is not a triangulation. We can nevertheless proceed to define a finite element space $V$ on this mesh, using linear Lagrange elements with the $C^{0}$ geometric decomposition assigning each nodal variable to its vertex.
(i) Show that $V$ is not a $C^{0}$ finite element space.
(ii) Describe, with justification, a subspace of $V$ containing only $C^{0}$ functions. (2 marks)
(d) We consider the finite element discretisation of the equation $u-\nabla^{2} u=f$ on the unit square $\Omega$ with boundary conditions $\frac{\partial u}{\partial n}=0$ on all edges. For a $C^{0}$ finite element space $W$, the finite element discretisation seeks $u_{h} \in W$ such that

$$
\begin{equation*}
\int_{\Omega} u_{h} v+\nabla u_{h} \cdot \nabla v \mathrm{~d} x=\int_{\Omega} v f \mathrm{~d} x, \quad \forall v \in W \tag{11}
\end{equation*}
$$

We say that a finite element discretisation is consistent if replacing $u_{h}$ with the exact solution $u$ to the strong form partial differential equation still gives equality for all test functions.
Provide a modification to (11) with the two following properties:

1. The resulting finite element discretisation is consistent.
2. The modification vanishes when $u_{h}$ vanishes on the interior edge going from bottom left to top right in the diagram in Figure 1.
(4 marks)
(Total: 20 marks)
3. For a convex polygonal domain $\Omega$, we consider a variational problem on $H^{1}(\Omega)$, seeking $u \in H^{1}(\Omega)$ such that

$$
\begin{equation*}
a(u, v)=F[v], \quad \forall v \in H^{1}(\Omega) \tag{12}
\end{equation*}
$$

where $a$ and $F$ are bilinear and linear forms on $H^{1}(\Omega)$, respectively. Further, we assume that $a$ is symmetric.
(a) (i) State what it means for $a(\cdot, \cdot)$ to be coercive.
(ii) State what it means for $a(\cdot, \cdot)$ to be continuous.
(iii) State what it means for $F$ to be continuous.
(iv) Write down a Galerkin finite element approximation to our variational problem, using a finite element space $V \subset H^{1}(\Omega)$.
(b) (i) Show that

$$
\begin{equation*}
a\left(u-u_{h}, v\right)=0, \quad \forall v \in V \tag{13}
\end{equation*}
$$

where $u_{h}$ is the finite element approximation to the solution $u$.
(ii) What does this tell us about the error in the solution?
(c) Using the earlier parts of this question, and assuming that $a$ is continuous and coercive, show that

$$
\begin{equation*}
\left\|u-u_{h}\right\|_{H^{1}(\Omega)} \leq C \sup _{v \in V}\|v-u\|_{H^{1}(\Omega)}, \tag{14}
\end{equation*}
$$

for some constant $0<C \leq \infty$.
5. In this question, we consider the Stokes equations, written in strong form as

$$
\begin{equation*}
-2 \mu \nabla \cdot \epsilon(u)+\nabla p=f, \quad \nabla \cdot u=0 \tag{15}
\end{equation*}
$$

for (vector valued) velocity $u$ and (scalar valued) pressure $p$, where

$$
\begin{equation*}
\epsilon(u)=\frac{1}{2}\left(\nabla u+(\nabla u)^{T}\right) . \tag{16}
\end{equation*}
$$

We consider boundary conditions $u=0$ on the boundary $\partial \Omega$ of the 3-dimensional domain $\Omega$.
The variational formulation seeks $(u, p) \in(V, Q)$, where $V=\left(H^{1}\right)^{3}$ is the subspace of $\left(H^{1}\right)^{3}$ vanishing on the boundary, and $Q=\check{L}^{2}$ is the subspace of $L^{2}$ that integrates to zero, such that

$$
\begin{equation*}
c((u, p),(v, q))=\int_{\Omega} f \cdot v \mathrm{~d} x, \quad \forall(v, q) \in\left(\dot{H}^{1}(\Omega)\right)^{3} \times \stackrel{\circ}{L}^{2}(\Omega) \tag{17}
\end{equation*}
$$

where

$$
\begin{array}{r}
c((u, p),(v, q))=a(u, v)+b(v, p)+b(u, q), \\
a(u, v)=2 \mu \int_{\Omega} \epsilon(u): \epsilon(v) \mathrm{d} x, \quad b(u, q)=\int_{\Omega} p q \mathrm{~d} x \tag{19}
\end{array}
$$

(a) Show that if $(u, p)$ solves the variational formulation, and further that $u \in H^{2}(\Omega)$ and $p \in H^{1}(\Omega)$, then $(u, p)$ solves the strong form of the Stokes equations.
(b) Show that the form $c((u, p),(v, q))$ is not coercive.
(c) Now we consider the discrete inf-sup condition, which requires that there exists $\beta_{h}>0$ such that

$$
\begin{equation*}
\inf _{0 \neq q \in Q_{h}} \sup _{0 \neq v \in V_{h}} \frac{b(v, q)}{\|v\|_{V}\|q\|_{Q}} \geq \beta_{h} \tag{20}
\end{equation*}
$$

for finite element spaces $V_{h} \subset V$ and $Q_{h} \subset Q$. We define $B^{*}$ as the map from $Q$ to the dual space $V^{\prime}$, given by

$$
\begin{equation*}
\left(B^{*} q\right)[v]=b(v, p), \quad \forall q \in Q, v \in V \tag{21}
\end{equation*}
$$

We also define $B_{h}^{*}$ as the map from $Q_{h}$ to the dual space $V_{h}^{\prime}$, given by

$$
\begin{equation*}
\left(B_{h}^{*} q\right)[v]=b(v, p), \quad \forall q \in Q_{h}, v \in V_{h} . \tag{22}
\end{equation*}
$$

Show that if $B_{h}^{*}$ has a kernel, then the discrete inf-sup condition is not satisfied. (4 marks)
(d) Consider a mesh of squares, with each square subdivided into four triangles by the diagonals. When $V_{h}$ is constructed from continuous linear elements (with the boundary condition subspace restriction) and $Q_{h}$ is constructed from discontinuous constant elements (with the mean zero restriction), show that $\operatorname{ker}\left(B_{h}^{*}\right)$ is not empty.

